

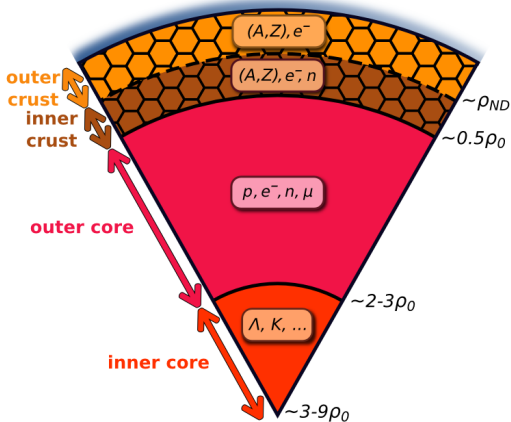
Numerical models for superfluid neutron stars & application to pulsar glitches

Aurélien Sourie
in collaboration with
Jérôme Novak & Micaela Oertel

Laboratoire Univers et Théories
Observatoire de Paris - Meudon

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Superfluidity in neutron stars



Theoretical considerations

[Baym, Pethick & Pines, *Nature*, 1969 & Pines & Alpar, *Nature*, 1985]

$$T \lesssim T_c \sim 10^9 - 10^{10} \text{ K}$$

- **superfluid neutrons** in the core & in the inner crust,
- **superconducting protons** in the core.

[adapted from Langlois, "Superfluidity in relativistic neutron stars", 2002 & Haensel, Potekhin & Yakovlev, "Neutron stars 1 : Equation of state and structure", 2007.]

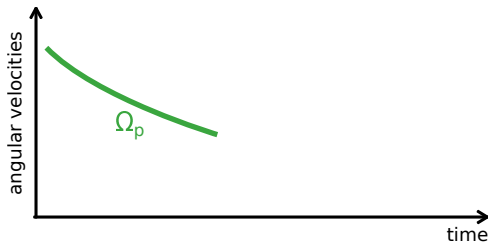
Two-fluid model

Consequence of superfluidity:

several **dynamically distinct** components inside neutron stars.

Two fluids

- Charged particles:
 $\Omega_p = \Omega$ (\rightarrow pulsar)



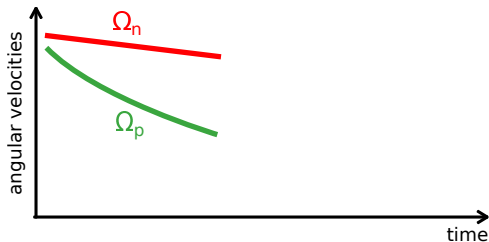
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- Superfluid neutrons:
 $\Omega_n \gtrsim \Omega_p$



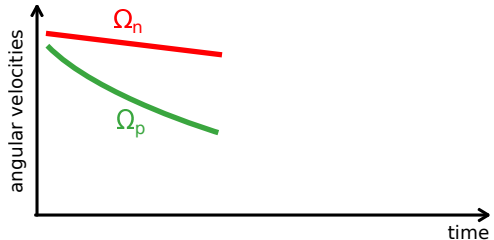
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Couplings:

- **Entrainment** (non dissipative)
- **Mutual friction** (dissipative)

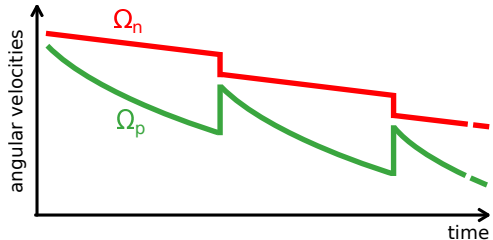
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Couplings:

- **Entrainment** (non dissipative)
- **Mutual friction** (dissipative) \rightarrow **glitches**

Evidence for superfluidity

[Anderson & Itoh, *Nature*, 1975]

Long relaxation time scales observed in *pulsar glitches*.

Purposes of the present work

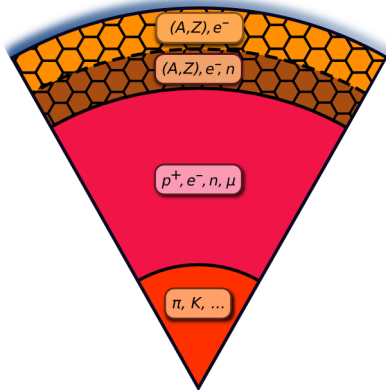
Previous works:

- *Theoretical* model with two fluids in GR developed by **Carter, Langlois, et al.** (1990s).
- **Prix, Novak & Comer, PRD, 2005**: *Numerical* model for stationary superfluid neutron stars implemented in LORENE.
--> polytropic EoS (non realistic).

Purposes

- Compute equilibrium configurations of rotating superfluid neutron stars considering 2-fluid EoSs based on microphysics,
- Give a simple numerical model concerning pulsar glitches.

Basic assumptions



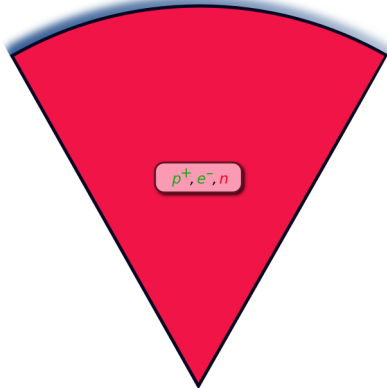
Equilibrium configurations

- isolated star,
- $T = 0$,
- no magnetic field,
- dissipative effects are neglected,
- uniform composition $\rightarrow p, e^-, n$,
- asymptotically flat, stationary, axisymmetric & circular metric,
- rigid-body rotation: Ω_n, Ω_p .

System = two **perfect** fluids coupled by *entrainment*:

- superfluid neutrons $\rightarrow \vec{n}_n = n_n \vec{u}_n$,
- protons & electrons $\rightarrow \vec{n}_p = n_p \vec{u}_p$.

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Canonical two-fluid hydrodynamics

[Carter, "Covariant theory of conductivity in ideal fluid or solid media", 1989, Comer & Langlois, *CQG*, 1994, Carter & Langlois, *PRD*, 1995 & Carter & Langlois, *Nuc. Phys. B*, 1998.]

Energy-momentum tensor

$$T_{\alpha\beta} = n_{n\alpha} p_{\beta}^n + n_{p\alpha} p_{\beta}^p + \Psi g_{\alpha\beta}$$

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Entrainment matrix:

$$\begin{cases} p_{\alpha}^n &= \mathcal{K}^{nn} n_{\alpha}^n + \mathcal{K}^{np} n_{\alpha}^p \\ p_{\alpha}^p &= \mathcal{K}^{pn} n_{\alpha}^n + \mathcal{K}^{pp} n_{\alpha}^p \end{cases}$$

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⇒ entrainment effect

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\Rightarrow **entrainment effect**

$$\longrightarrow \begin{cases} p_{\alpha}^n &\propto u_{\alpha}^n \\ p_{\alpha}^p &\propto u_{\alpha}^p \end{cases}$$

without entrainment

Equation of State

$$\mathcal{E}(n_n, n_p, \Delta^2) \leftrightarrow \Psi(\mu^n, \mu^p, \Delta^2)$$

First law of thermodynamics (T=0)

$$d\mathcal{E} = \mu^n dn_n + \mu^p dn_p + \alpha d\Delta^2$$

Relativistic Mean-Field Theory:

nucleon-nucleon interactions \Leftrightarrow exchange of effective mesons

$$\mathcal{L} = \underbrace{\mathcal{L}_b}_{\text{free baryons}} + \underbrace{\mathcal{L}_\sigma + \mathcal{L}_\omega + \mathcal{L}_\rho + \mathcal{L}_\delta}_{\text{free mesons}} + \underbrace{\mathcal{L}_{\text{int}}}_{\text{interaction}}$$

EoSs:

- DDH (without δ meson)
- DDH δ (with δ meson)

--> adapted to a two-fluid system coupled by entrainment.

[Comer & Joynt, 2003 & Gusakov, Kantor & Haensel, 2009.]

Entrainment effects

Dynamical effective mass:

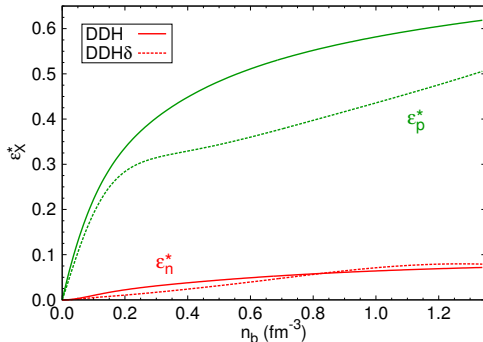
$${}^3\vec{p}_X = m_X^* {}^3\vec{u}_X$$

↪ in the *rest frame* of the second fluid.

Zero-velocity frame

$$m_X^* = \mu^X (1 - \varepsilon_X^*)$$

$$\hookrightarrow \varepsilon_X^* = \frac{2\alpha}{n_X \mu^X}$$

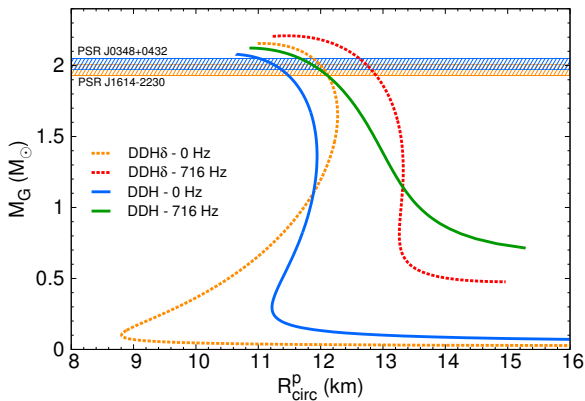


↪ assuming β -equilibrium & $\Delta^2 = 0$.

Global quantities

Surface definitions

$$n_n = 0 \text{ \& \ } n_p = 0$$



- Gravitational mass:

$$M_G = M^B + E_{\text{bind}},$$

- Circumferential radius:

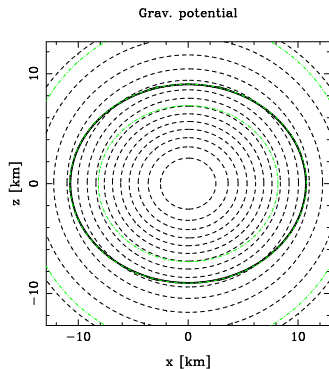
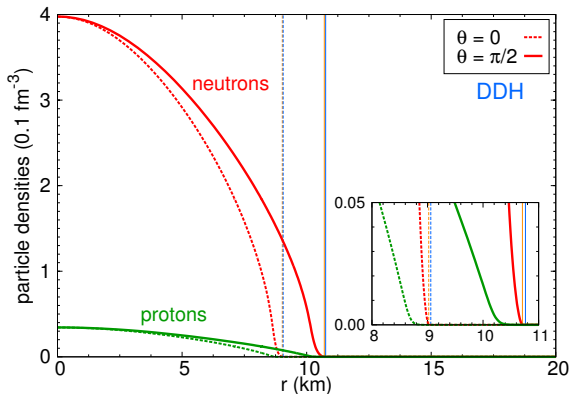
$$R_{\text{circ, eq}}^X = c^X / 2\pi.$$

Virial identities:

$$GRV \sim 10^{-7} - 10^{-5}$$

Density profiles

$$M_G = 1.4 M_\odot, \Omega_n/2\pi = \Omega_p/2\pi = 716 \text{ Hz}$$

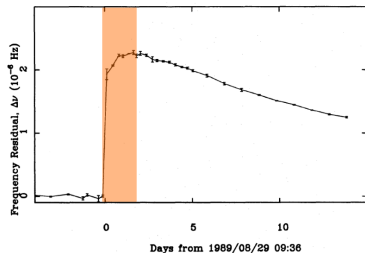


$$\rightarrow n_b(0) \simeq 0.44 \text{ fm}^{-3} \ \& \ x_p(0) \simeq 0.08.$$

Modelling glitch rise

Bulk model for pulsar glitches:

$\Delta\Omega \gtrsim \Delta\Omega_c \Rightarrow$ angular momentum transfer through **mutual friction**



[Lyne, Pritchard & Smith, *MNRAS*, 1993.]

Typical time scales

- **rise time:**

$$\begin{cases} \tau_r \lesssim 40 \text{ s} - 2 \text{ min} & \text{Vela} \\ \tau_r \sim \text{a few hours} & \text{Crab} \end{cases}$$

[Dodson, McCulloch & Lewis, *ApJL*, 2002 & Lyne, Pritchard & Smith, *MNRAS*, 1993.]

- **dynamical time:**

$$\tau_{\text{dyn}} \simeq 0.1 \text{ ms}$$

[Epstein, *ApJ*, 1988 & Shapiro, *ApJ*, 2000.]

---> Series of **equilibrium** configurations with **constant** M^B and J .

Angular momentum transfer

Evolution equations:

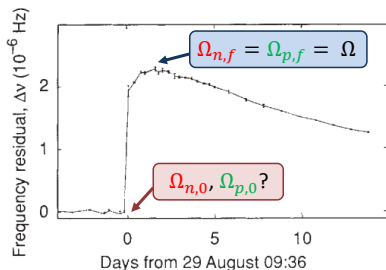
$$\begin{cases} \dot{J}_n &= + \Gamma_{int}, \\ \dot{J}_p &= - \Gamma_{int}. \end{cases}$$

Mutual friction moment

[Langlois, Sedrakian & Carter, *MNRAS*, 1998 &
 Sidery, Passamonti & Andersson, *MNRAS*, 2010.]

$$\Gamma_{int} = \mathcal{B} (\Omega_p - \Omega_n) \int \Gamma_n n_n \varpi_n h_{\perp}^2 d\Sigma$$

↪ Computation of $\Omega_n(t)$ & $\Omega_p(t)$ profiles from $\Omega_{n,0} > \Omega_{p,0}$



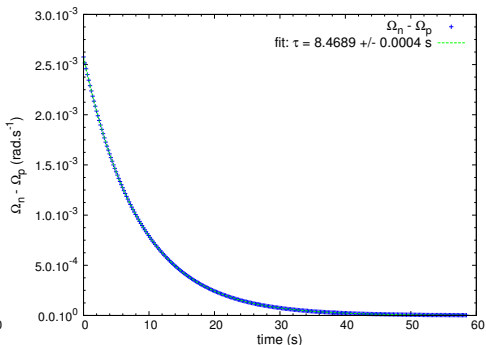
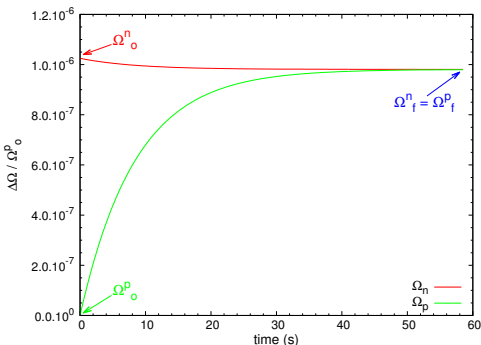
Initial lag = trigger threshold:

$$\Delta\Omega_c = \Omega_{n,0} - \Omega_{p,0} \simeq 10^{-9} - 10^{-5} \Omega$$

Preliminary results

Inputs:

$$\Delta\Omega/\Omega = 10^{-6}, \Omega_f^n/2\pi = \Omega_f^p/2\pi = 400 \text{ Hz}, M^B = 1.7 M_\odot \text{ \& } \mathcal{B} = 10^{-6}$$



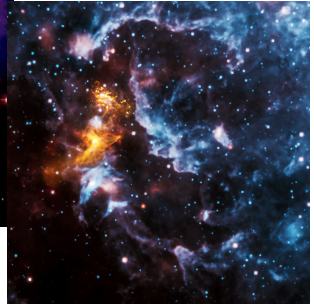
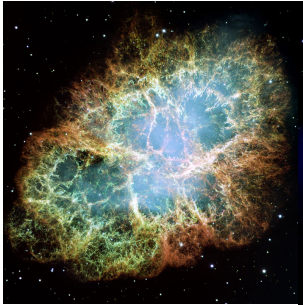
$$\Omega_n(t) - \Omega_p(t) \propto e^{-t/\tau_r} \Rightarrow \tau_r \sim 8.5 \text{ s}$$

Conclusion

- Equilibrium configurations for superfluid neutron stars with realistic EoSs, using LORENE,
- Bulk model for pulsar glitches seen as angular momentum transfers through mutual friction force, in GR.

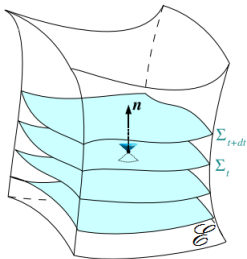
Future work:

- τ_r as a function of \mathcal{B} , M^B , ... for different EoSs,
- Confrontation with accurate observations of glitches,
- Evolution in time of mass quadrupole $Q \rightarrow$ GWs.



Thank you!

Formalisme 3+1



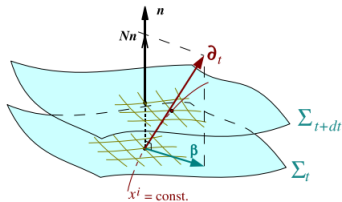
Feuilletage de l'espace-temps $(\mathcal{E}, \mathbf{g})$ par $(\Sigma_t)_{t \in \mathbb{R}}$, de normale (locale) unitaire \vec{n}

Observateurs **eulériens** \mathcal{O}_n : 4-vitesse = \vec{n}

- Fonction **lapse** N : $\vec{n} = -N\vec{\nabla}t$,
- Vecteur **shift** $\vec{\beta}$: $\vec{\partial}_t = N\vec{n} + \vec{\beta}$.

Métrie 3+1 :

$$g_{\alpha\beta} dx^\alpha dx^\beta = -N^2 dt^2 + \gamma_{ij} (dx^i + \beta^i dt) (dx^j + \beta^j dt)$$



Résolution numérique : méthode du point fixe

Paramètres d'entrée :

- une EOS
- H_c^n , H_c^p
- Ω_n , Ω_p

$i = 0$

Initialisation :

- $N = A = B = 1$ et $\omega = 0, \forall (r, \theta)$
- $U_n = U_p = 0$
- $H_0^i(r, \theta) = H_c^i \left(1 - \frac{r^2}{R^2}\right)$

Test de convergence

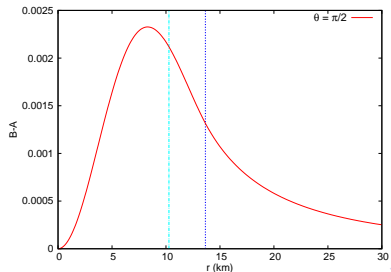
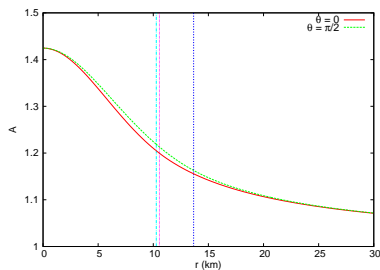
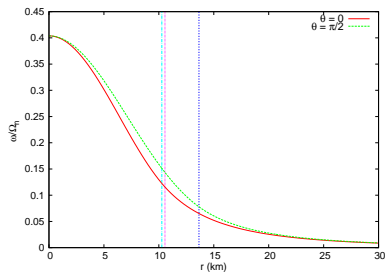
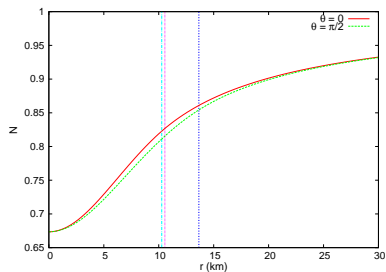
$$|H_{k+1}^i(r, \theta) - H_k^i(r, \theta)| < \epsilon$$

Étapes lors d'une itération

En chaque point (μ^n, μ^p, Δ^2) , on calcule :

1. Ψ , n_n , n_p et α à partir de l'EOS
2. Les termes sources E , p_φ , S^i_i ,
3. Résolution des équations d'Einstein,
4. Les termes cinétiques U_i et Γ_i ,
5. Calculs de H_{k+1}^i .

Résultats - coefficients métriques



Spacetime metric

[Bonazzola, Gourgoulhon, Salgado & Marck, *A&A*, 1993 & Prix, Novak & Comer, *PRD*, 2005.]

Rotating neutron stars, at **equilibrium**, described by $(\mathcal{E}, \mathbf{g})$:

- **asymptotically flat**: $\mathbf{g} \rightarrow \boldsymbol{\eta}$ at spatial infinity ($r \rightarrow +\infty$),
- **stationary** & **axisymmetric**: $\frac{\partial \mathbf{g}_{\alpha\beta}}{\partial t} = \frac{\partial \mathbf{g}_{\alpha\beta}}{\partial \varphi} = 0$,
- **circular**: perfect fluids \Rightarrow *purely circular* motion around the rotation axis with Ω_n, Ω_p (+ **rigid rotation**).

Spacetime metric in quasi-isotropic coordinates:

$$g_{\alpha\beta} dx^\alpha dx^\beta = -N^2 dt^2 + A^2(dr^2 + r^2 d\theta^2) + B^2 r^2 \sin^2 \theta (d\varphi - \omega dt)^2$$

At spatial infinity

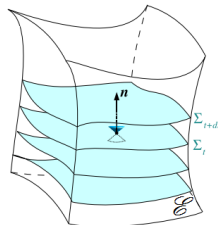
$$N, A, B \rightarrow 1 \quad \& \quad \omega \rightarrow 0$$

Angular momenta

Axisymmetry $\leftrightarrow \vec{\chi}$

Komar definition:

$$J_K = - \int_{\Sigma_t} \underbrace{\mathcal{T}(\vec{n}, \vec{\chi})}_{-p_\varphi} d^3V$$



Eulerian observer \vec{n} (3+1)

Angular momentum of each fluid

[Langlois, Sedrakian & Carter, *MNRAS*, 1998.]

$$p_\varphi = \underbrace{\Gamma_n n_n p_\varphi^n}_{j_\varphi^n} + \underbrace{\Gamma_p n_p p_\varphi^p}_{j_\varphi^p}$$

$$J_X = \int_{\Sigma_t} j_\varphi^X A^2 B r^2 \sin \theta dr d\theta d\varphi$$

Rk: $\Omega_X = 0 \not\Rightarrow J_X = 0$, if the second fluid is rotating!

Tabulated EoS

